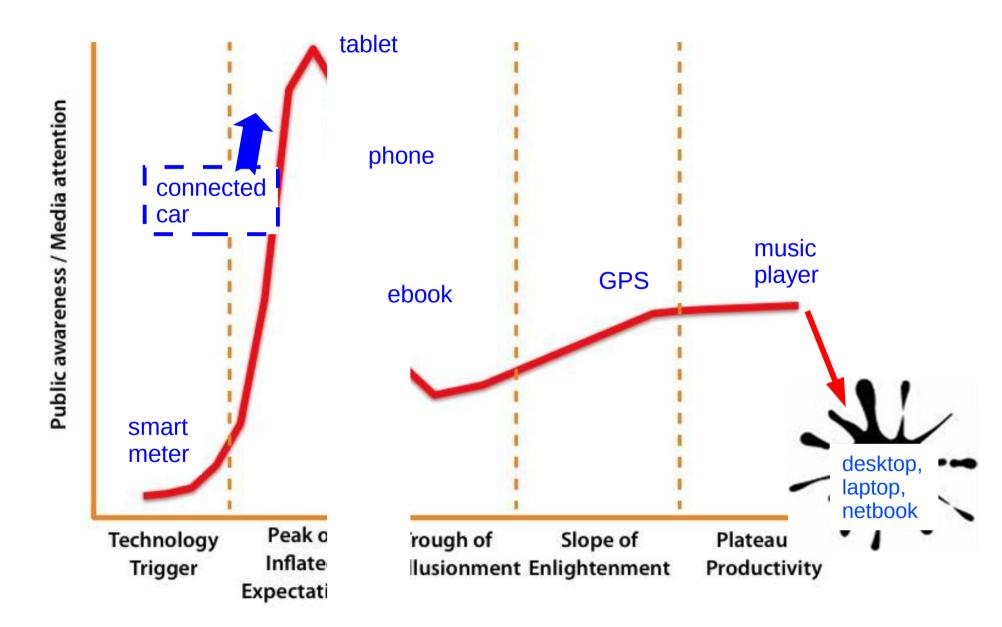
# The next frontier: open source in the car

Alison Chaiken alison@she-devel.com slideshare.net/chaiken, wiki.openice.org 4/11/12

- Who cares?
- Status report
- Opportunities for developers and businesses



# Gartner Hype Curve 2012



# Ford MyFord Touch Problems Prompt Company To Send Out Software Upgrade



By DEE-ANN DURBIN | 11/7/11 06:56 AM ET | AP



#### Status of Automotive Open Source

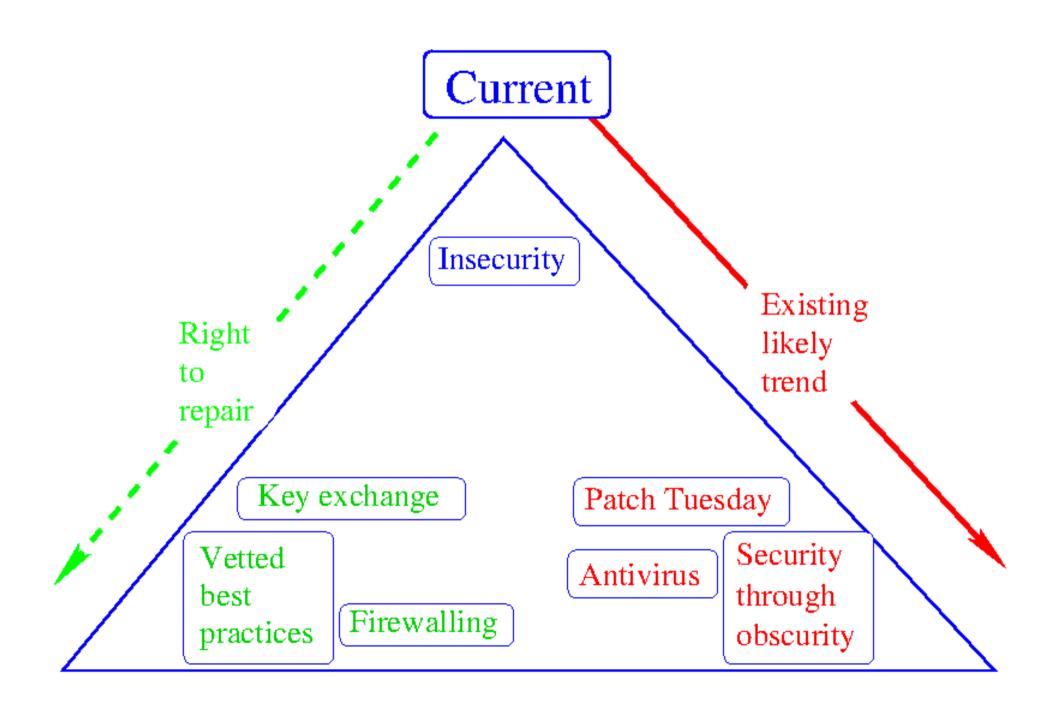
Manufacturer	Confirmed Operating system
Fiat-Chrysler Blue&Me (500, Delta), Kia Uvo, BYD, Nissan Leaf	Microsoft Windows Embedded Automotive
Ford (all?)	MyTouch/Sync-Microsoft; OpenXC-Android
General Motors (new 2012 Cadillacs), Chevy Volt	MontaVista's GNU/Linux
Geely (China); Hawtai (China)	GNU/Linux: Moblin (MeeGo predecessor)
Renault R-Link, Roewe 350	Android
Honda (Accord, Odyssey, Pilot), Audi, BMW (7-series and M models), Chrysler, Daewoo, GM (OnStar), Hyundai, Land Rover, Porsche, Saab (9-3) Renault (SM7)	QNX

Linux Foundation members: Toyota, Pelagicore, Symbio, Tieto.

Automotive Linux Summit 2011 presenters: Toyota, Nissan, BMW.

MeeGo Conference 2011 presenter: Nissan.

Volkswagen has a pilot using Maemo (Linux).



### How to get involved

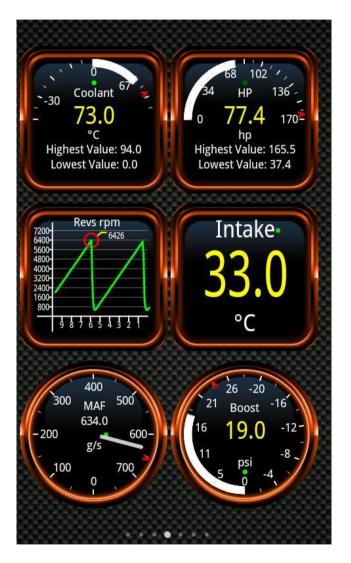
(or at least watch in an informed manner)

- Write apps for automotive platforms.
- Use cheap and readily available HW to interact with car.
- Integrate automotive data with other sets and mine for new purposes.
- Ask auto dealers, "What operating system does this model run?"
- Tell your Congresscritter you support the "Right to Repair" Act.

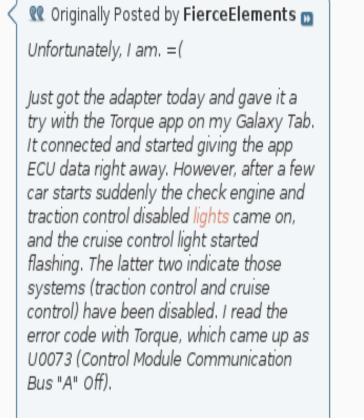
## Car manufacturer developer offerings

- Renault R-Link (Android): no car available in U.S.
- Ford's OpenXC Platform (Android and Arduinocompatible ChipKit32): launching May 2012.
- General Motors Cadillac User Experience: 2Q 2012 launch promised.
- Intel-Samsung (Tizen Linux with X11, HTML5) SDK: beta "preview".
- Ubuntu IVI Remix available for download now.

#### Proprietary "Torque" Android Market app and raw CAN



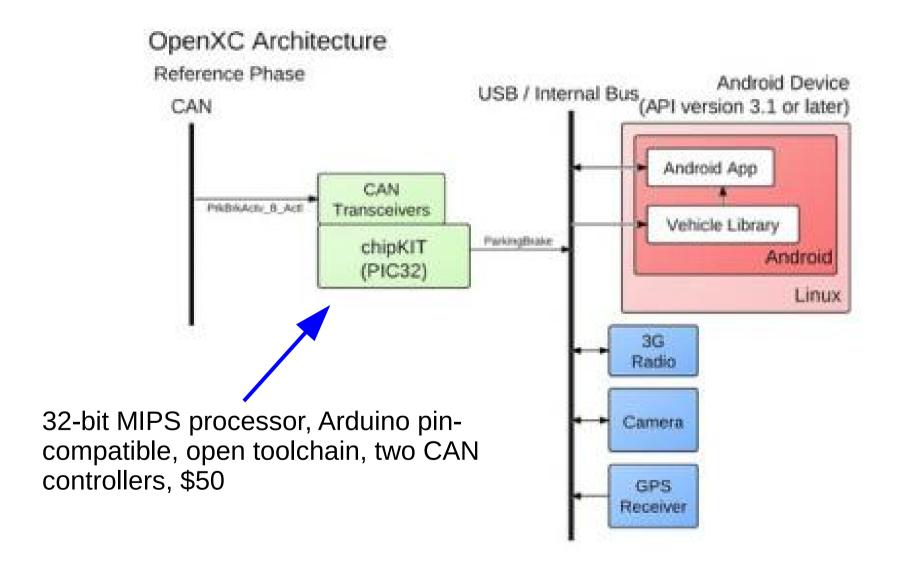




Source: very valuable mp3car.com forums

Pure OBDII completely safe!

## Ford's Android-Based OpenXC Platform



## BeagleBone from TI



\$89, widely available

CAN "cape" for BeagleBone



Runs QCanObserver based on Qt €79, available via mail-order

#### Quality community HW and SW already available



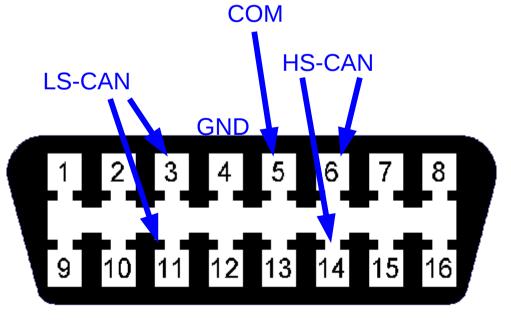
http://tinyurl.com/7wngdsj, http://tinyurl.com/7ttz24h

#### How to access a car's data



Determine protocols in use by examining populated pins.

OBDII connector found in every U.S. car since 1996.



2006 Mazda 3

#### How to select a scantool

- Check which pins are populated in the OBDII connector of your car.
  - Tells you which protocol(s) are supported.
- Need only 4, 5, 6, 14 for OBDII.
- Best choice for novice is USB ELM327:
  - Cheaper (less than \$50).
  - Won't drain car battery and won't write to CAN.
  - Easier to connect than Bluetooth.

#### About the OBDLink MX



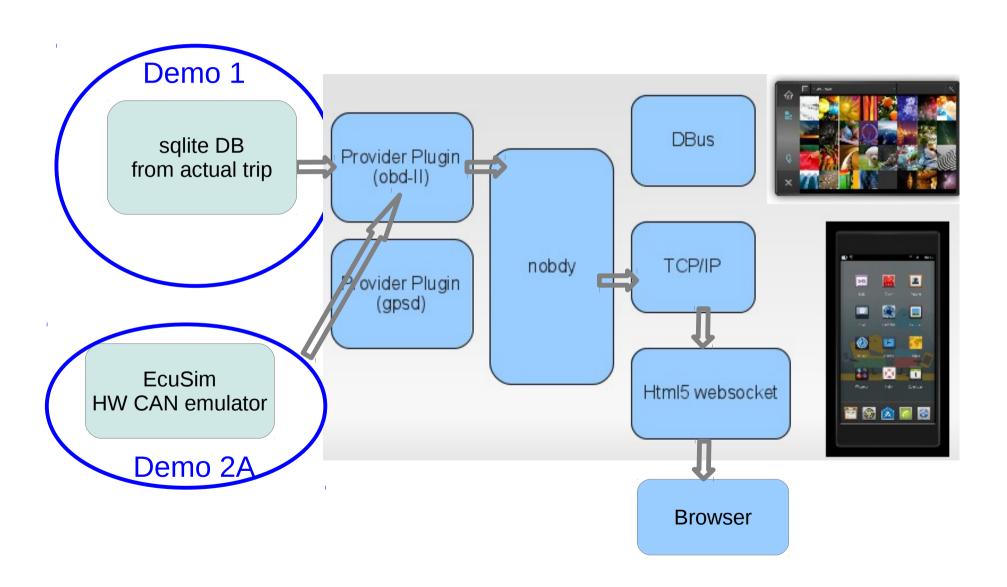
- Power-user choice.
- STN1110 controller (not ELM327), Bluetooth comms.
- Support OBDII and non-standard CAN bus
  - Typical "smog test" data plus
  - Doors, lights, wipers, key, locks . . .
- Reading OBDII is completely idiot-proof.
- Writing to CAN allows remote door unlock, headlight checking .

   or "bricking" of car!

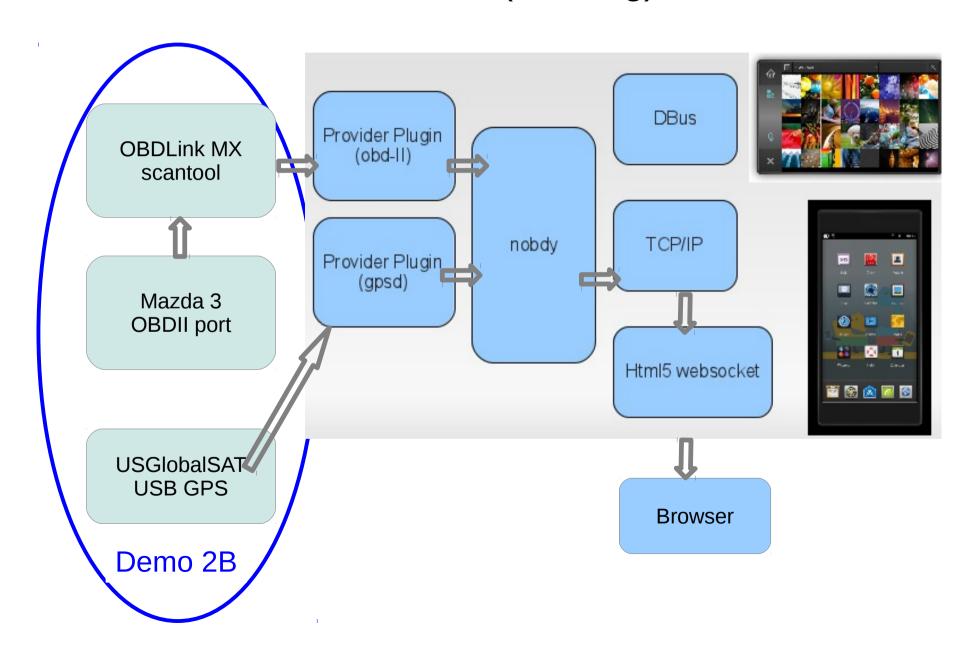
# Demo 1: replay of prerecorded trip using nOBDy



### <u>Demo 2A: live data demo using nOBDy, OBDLink MX</u> <u>and EcuSim (lunchtime)</u>



### <u>Demo 2B: live data demo using nOBDy, OBDLink MX</u> <u>and Mazda (evening)</u>



# **Summary**

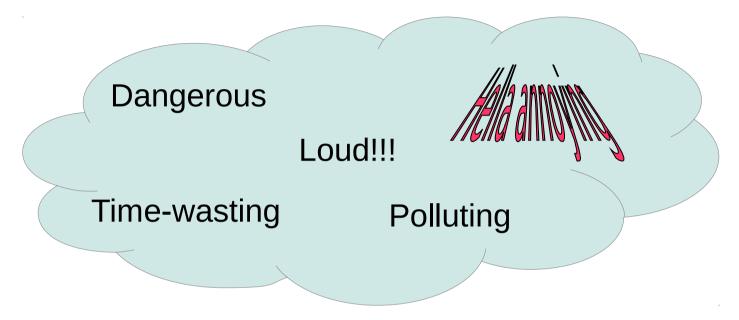
- Automotive open source is at a tipping point
- Opportunities to get involved as business, as hobby, as citizen
- Inexpensive HW and open-source SW solutions abound
- Join the party, or at least speak up for your rights!
- Visit us at openice.org, #linuxice on freenode IRC or mp3car.com

# chipKIT Max32™ Prototyping Platform



32-bit MIPS processor, Arduino pin-compatible, open toolchain, two CAN controllers, \$50

## Our transportation system is



because until now individuals had little power to change it.

Now: driver distraction

Goal: driver empowerment

Goal: driver augmentation